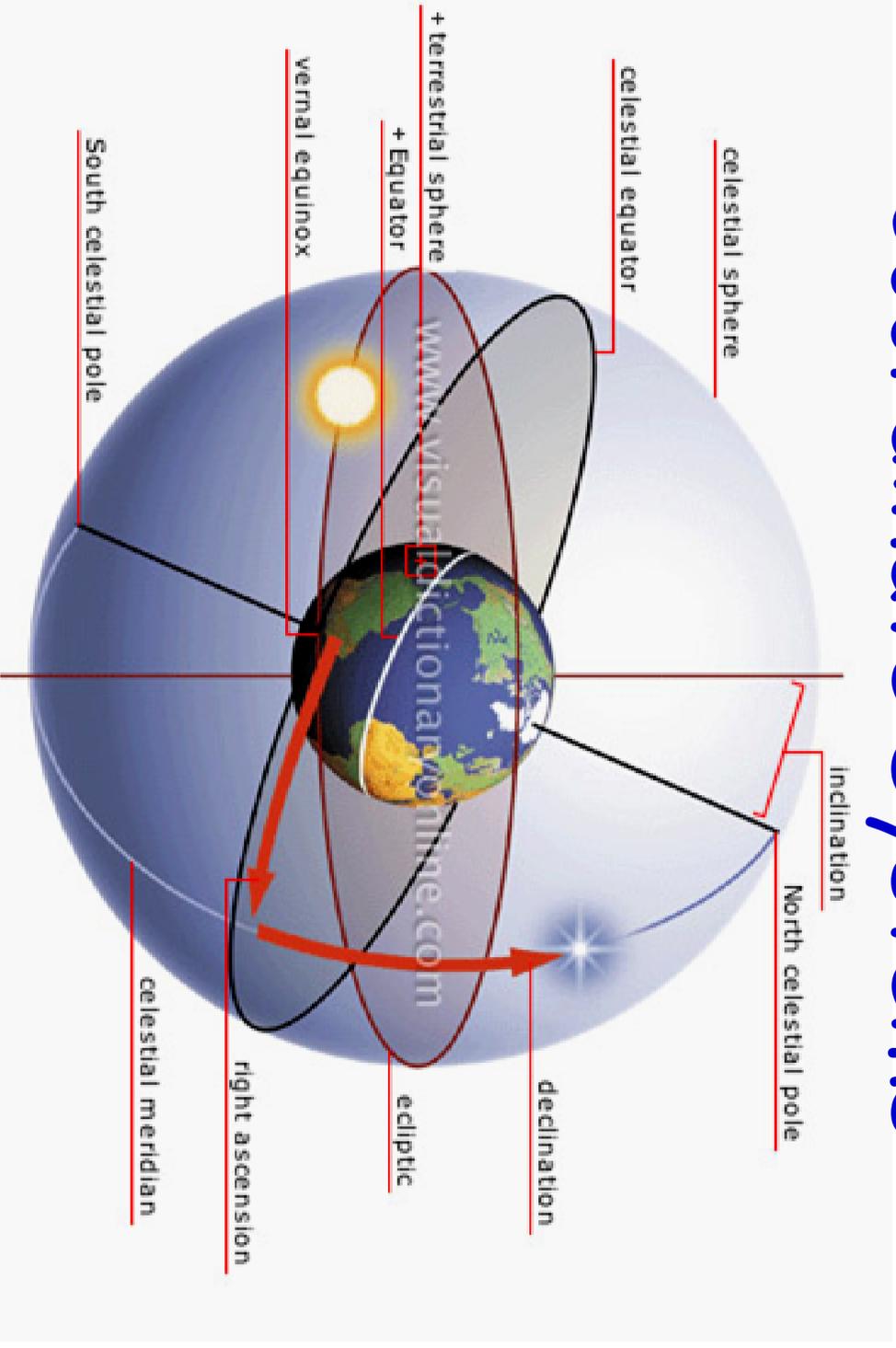


Coordinate Systems



Basis for any 3D Coordinate System

Basic steps for the **definition** of a 3D coordinate system:

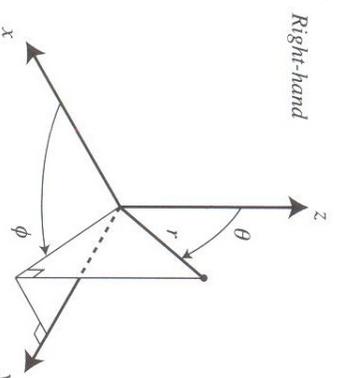
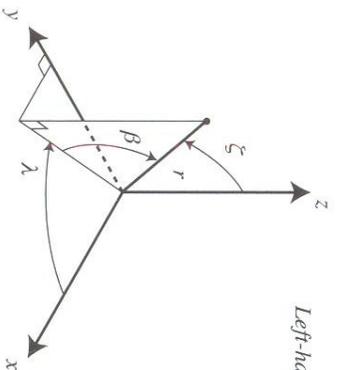
1. Locate the origin
2. Locate the x-y plane (the "fundamental plane")
3. Decide on direction of positive x axis ("reference direction")
4. Decide on sign convention of y and z axes

Usual approach to **define angles**:

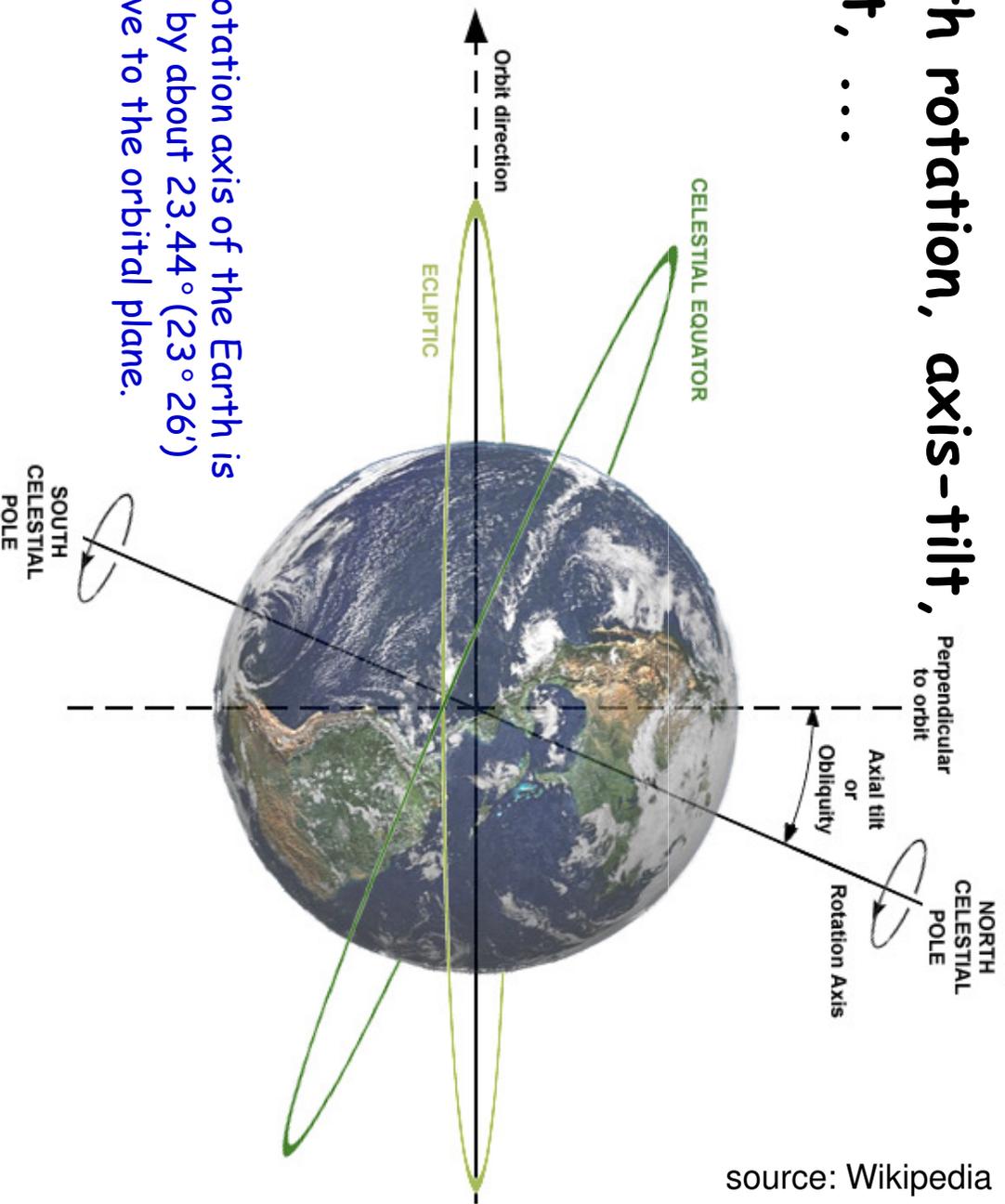
- First angle from +x to +y axis [$0 \leq \alpha, \phi, \lambda \leq 2\pi$]
- Second angle from x-y plane to +z axis [$-\pi/2 \leq \theta, \delta, \xi \leq +\pi/2$]
or [$0 \leq \theta, \delta, \xi \leq \pi$]

Left-hand

Right-hand



Earth rotation, axis-tilt, orbit, ...



source: Wikipedia

The rotation axis of the Earth is tilted by about 23.44° ($23^\circ 26'$) relative to the orbital plane.

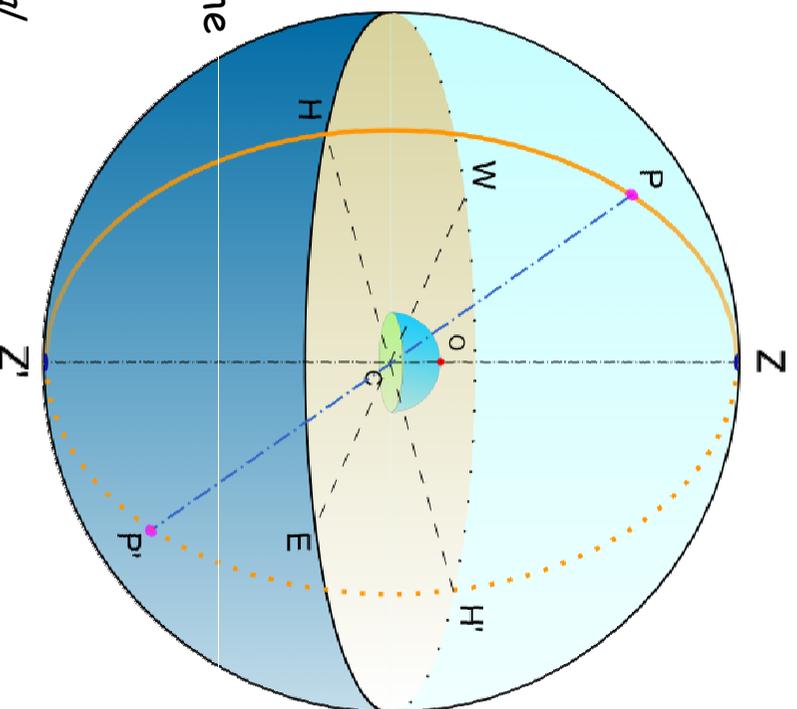
Definitions (1): the Meridian

A **meridian** is a great circle on the celestial sphere passing through:

- the north point on the horizon H
- the celestial pole P
- the zenith Z
- the south point on the horizon H'

The meridian is perpendicular to the local horizon.

Stars will appear to drift past the local meridian as the Earth spins.



source: Wikipedia

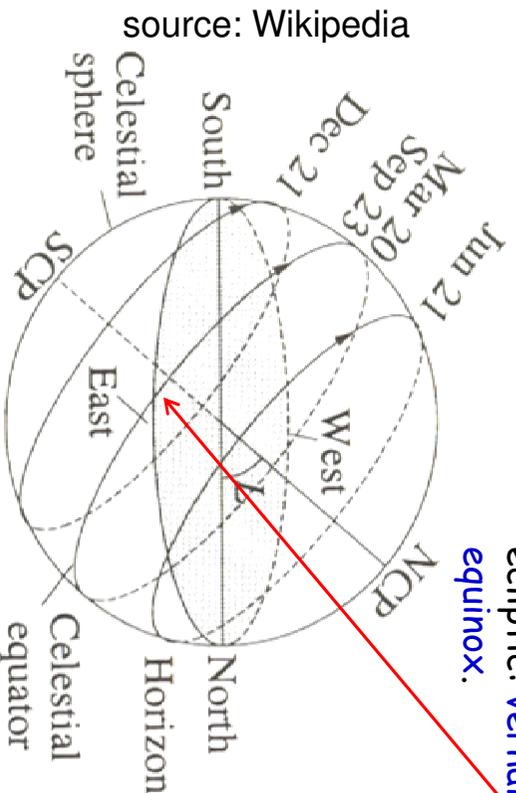
Definitions (2): Equinox

Equinox derives from 'aequus' (equal) and 'nox' (night).

Equinox = when the centre of the Sun can be observed to be directly above the Earth's equator (i.e., declination $\delta=0$).

At an equinox, the Sun will spend equal time above and below the horizon at every location on Earth.

Intersection point between celestial equator ($\delta=0$) and ecliptic: **vernal/autumnal equinox.**



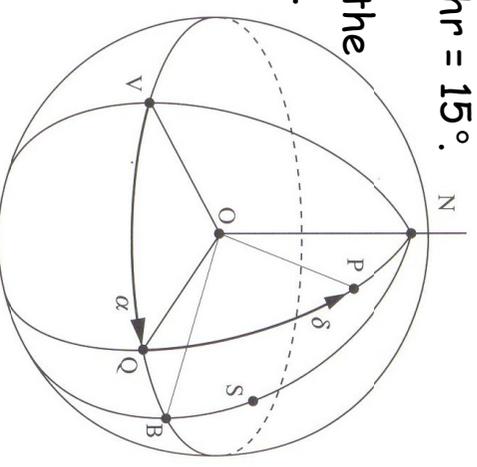
source: Wikipedia

UTC date and time of solstices and equinoxes ^[1]									
Year	Equinox		Solstice		Equinox		Solstice		Day
	Mar	Jun	June	Sept	Sept	Dec	Dec		
2004	20 06:49	21 00:57	22 16:30	21 12:42	2005	20 12:33	21 06:46	22 22:23	21 18:35
2006	20 18:26	21 12:26	23 04:03	22 00:22	2007	21 00:07	21 18:06	23 09:51	22 06:08
2008	20 05:48	20 23:59	22 15:44	21 12:04	2009	20 11:44	21 05:45	22 21:18	21 17:47
2010	20 17:32	21 11:28	23 03:09	21 23:38	2011	20 23:21	21 17:16	23 09:04	22 05:30
2012	20 05:14	20 23:09	22 14:49	21 11:12	2013	20 11:02	21 05:04	22 20:44	21 17:11
2014	20 16:57	21 10:51	23 02:29	21 23:03	2015	20 22:45	21 16:38	23 08:20	22 04:48
2016	20 04:30	20 22:34	22 14:21	21 10:44	2017	20 10:28	21 04:24	22 20:02	21 16:28

Def. (3): Hour Angle and Right Ascension

The **hour angle** is the angle between the meridian plane and the half plane determined by the Earth's axis and the given point. The hour angle is expressed in time units, with one hour = $360^\circ/24\text{hr} = 15^\circ$.

The **right ascension** α is the angle VOQ between the vernal equinox and the given point on the equator.



The **hour angle** is also the difference between **local sidereal time (LST)** and **right ascension** α :

$$H_{\text{Object}} = \text{LST} - \alpha_{\text{Object}}$$

The object's hour angle indicates how much sidereal time has passed since the object was on the local meridian.

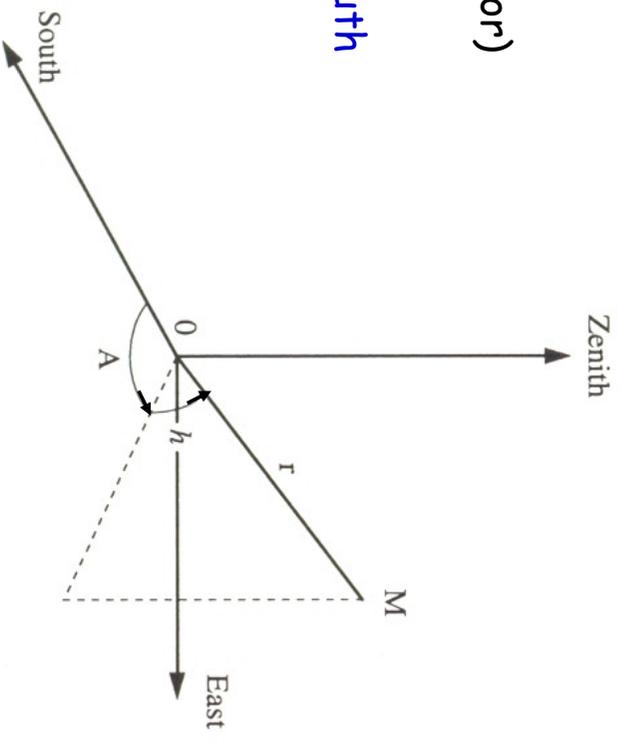
I. The Horizontal Frame (Alt-Azimuth)

Origin: Position of the observer

Axes: local vertical (gravity vector)
horizon

Coordinates: azimuth A from South
height h

$$U(A, h) = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \cos A \cos h \\ \sin A \cos h \\ \sin h \end{bmatrix}$$



Problem: apparent motion of the celestial sphere.

Note: due to tidal forces the gravity vector changes and hence the coordinates relative to surface structures by typically 0.015"

II. The Hour Frame (Latitude-Longitude)

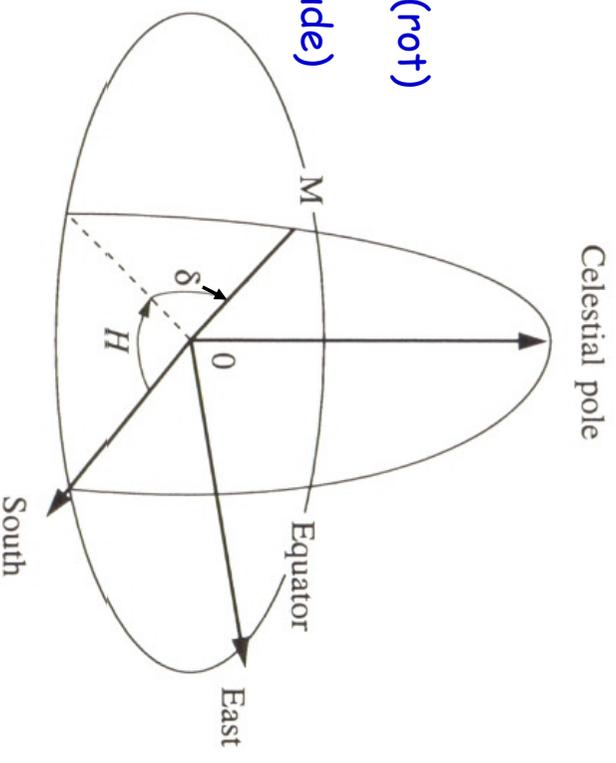
Choose celestial equator as fundamental plane.

Origin: Position of the observer

Axes: vector to celestial pole
vector to celestial equator (rot)

Coordinates: declination δ (latitude)
hour angle H

$$U(H, \delta) = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \cos H \cos \delta \\ -\sin H \cos \delta \\ \sin \delta \end{bmatrix}$$



Problem: refers to the observer's local meridian.

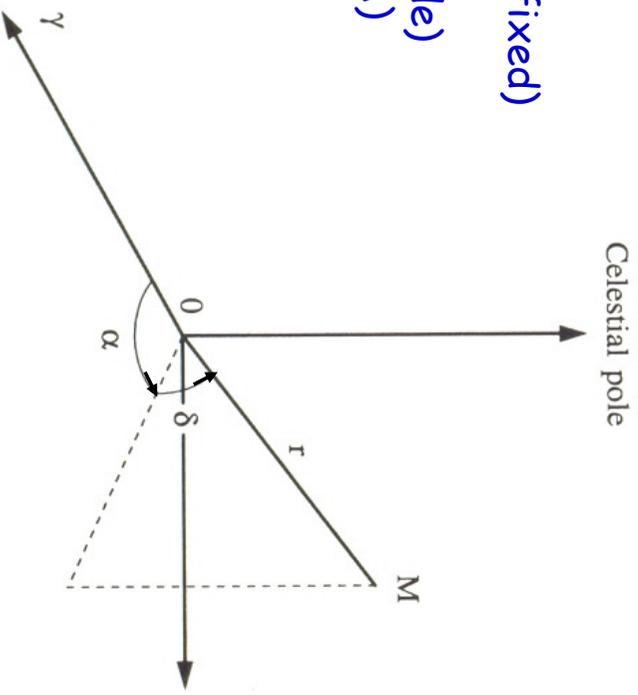
III. The Equatorial Frame

Removes the largest component of Earth rotation

Axes: **vector to celestial pole**
vector to celestial equator (fixed)

Coordinates: **declination δ (latitude)**
right ascension α (RA)

$$U(\alpha, \delta) = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \cos \alpha \cos \delta \\ \sin \alpha \cos \delta \\ \sin \delta \end{bmatrix}$$



The equatorial frame is used for most star and galaxy catalogues.

PPM J2000.0 +80 degrees Stars No. 2401 ff

PPM	DM	Maj Sp	R.A. J2000	Dec. J2000	PMA	PMD	N SA	SD	SPMA	SPMD	EPA	EPD	SAO	HD	AGK3	Notes
01	+88 0084	10.8 G0	13 41 7.059	+87 54 45.48	0.0022	0.005	9 07 06	2.2	1.9	44.10	43.94	2296				+88 0076 H
02	+84 0316	11.2 F5	13 41 10.613	+83 25 29.66	-0.0091	0.000	4 12 12	5.3	5.4	23.00	24.78	2263				+83 0356 H
03	+81 0445	11.1 G8	+81 21.575	+81 3 40.88	0.0064	0.011	4 12 12	5.4	5.5	24.15	26.00	2261				+81 0417 H
04	+87 0130	10.3 G5	13 41 33.285	+86 35 55.03	0.0024	-0.021	7 07 07	2.3	2.1	49.34	49.71	2276				+86 0193 H
05	+80 0421	8.5 K5	13 41 38.768	+80 12 13.06	-0.0128	0.001	7 06 07	2.3	2.4	54.13	51.57	2262	120103			+80 0305 H
06	+83 0397	6.0 F5	13 42 23.092	+82 45 8.62	0.0183	-0.041	0 02 02	0.8	0.7	56.42	40.97	2266	120565			+83 0357 F
07	+81 0446	11.0 F2	13 42 33.663	+80 24 7.97	-0.0045	-0.009	5 10 10	4.5	4.4	23.67	23.85	2264				+80 0306 H
08	+81 0447	9.8 K0	13 42 52.566	+80 43 25.36	-0.0113	-0.005	9 07 06	2.1	1.9	44.61	44.34	2265	120363			+80 0292 H
09	+88 0085	10.2 K0	13 43 5.608	+87 51 5.97	0.0695	-0.017	5 08 09	3.9	4.1	39.32	37.45	2301				+88 0077 H
10	+86 0198	11.2 G5	13 43 26.319	+85 42 26.46	0.0005	-0.024						2277				+85 0213 H
11	+82 0403	11.4 G5	13 43 26.894	+81 32 47.03	-0.0136	-0.026	4 12 12	5.4	5.4	22.53	24.31	2269				+81 0418 H
12	+87 0132	12.4 K2	13 44 9.617	+86 50 13.77	0.0161	-0.004	7 07 07	2.5	2.3	51.11	53.38	2286				+87 0105 H
13	+81 0438	10.7 K0	13 44 25.170	+80 34 24.98	-0.0069	-0.023	4 12 11	5.3	5.2	25.71	26.18	2271				+80 0308 H
14	+85 0234	8.8 K0	13 45 31.538	+84 30 47.16	-0.0025	-0.010	7 07 07	2.0	2.0	50.28	51.08	2280	121623			+84 0292 H
15	+86 0199	9.6 F5	13 45 48.743	+85 31 24.81	-0.0121	0.022	8 07 07	3.1	3.1	34.58	31.03	2284	122103			+85 0214 H
16	+83 0398	10.8 G5	13 46 27.094	+82 31 46.99	0.0016	-0.029	4 12 11	5.2	5.0	24.71	24.86	2278				+82 0399 H
17	+81 0449	10.5 K0	13 47 4.418	+81 16 24.02	0.0065	-0.018	4 11 11	5.2	5.1	26.23	26.70	2279				+81 0419 H
18	+84 0317	9.7 F0	13 47 18.812	+84 6 56.58	0.0042	0.013	5 10 10	4.3	4.1	23.81	23.73	2283				+84 0293 H
19	+88 0087	11.2 A5	13 48 12.656	+87 55 34.91	-0.0146	0.002	6 07 06	2.1	1.9	43.60	45.57	2318				+88 0078 H
20	+85 0235	9.8 K2	13 48 18.527	+85 11 55.70	-0.0001	0.003	6 07 08	3.4	3.4	36.98	33.67	2282	122362			+85 0215 H
21	+81 0450	11.4 F5	13 48 32.674	+80 21 1.44	0.0012	-0.004	4 12 13	5.6	5.7	24.31	26.35	2281				+80 0309 H
22	+86 0240	7.5 F0	13 49 15.571	+85 44 52.53	-0.0370	0.024	8 05 06	2.3	2.4	52.79	52.75	2298	122882			+85 0216 H
23	+84 0318	10.9 G5	13 49 17.550	+83 58 57.13	0.0198	-0.005	4 12 11	5.3	5.1	24.42	24.57	2290				+84 0294 H
24	+88 0088	11.2 G0	13 49 51.617	+88 7 39.75	-0.0148	-0.010	8 08 08	3.2	3.2	31.12	29.01	2327				+88 0079 H
25	+81 0451	11.2 K0	13 49 55.547	+80 55 14.32	-0.0031	-0.005	4 12 12	5.4	5.5	23.82	25.69	2285				+81 0420 H
26	+83 0399	11.5 K0	13 50 1.940	+82 18 47.07	-0.0019	0.010	4 13 12	5.6	5.3	24.50	23.78	2287				+82 0400 H
27	+86 0202	10.2 F5	13 50 4.531	+85 54 56.01	-0.0093	0.004	5 09 08	2.6	2.5	51.18	50.54	2279				+86 0194 H
28	+83 0401	11.7 G	+82 54 47.92	+82 54 47.92	0.0021	0.017	4 13 12	5.6	5.3	24.51	23.80	2293				+83 0359 H
29	+83 0400	11.6 G	13 50 22.800	+82 52 42.81	0.0024	0.000	4 13 12	5.6	5.3	24.50	23.78	2291				+83 0358 H
30	+81 0452	7.7 K0	13 51 0.570	+80 46 4.28	0.0178	-0.011	6 08 08	2.3	2.3	50.52	52.71	2292				+81 0421 H
31	+87 0134	10.9 G0	13 51 29.816	+87 14 27.95	-0.0224	-0.014	7 08 08	3.3	3.2	34.02	30.31	2315				+87 0106 H
32	+84 0320	11.1 G0	13 51 29.995	+84 4 17.356	-0.0106	0.008	4 12 12	5.3	5.3	23.34	25.11	2299				+84 0295 H
33	+89 0031	11.4 G8	13 51 39.885	+89 15 23.87	0.0197	-0.000	14 08 06	2.4	1.8	34.24	34.41	2450				+89 0038 H
34	+81 0453	11.0 G2	13 52 12.812	+80 48 27.30	0.0129	-0.045	4 12 12	5.3	5.5	24.66	26.30	2295				+81 0422 H
35	+82 0404	11.3 G0	13 52 18.733	+81 59 29.03	0.0074	-0.070	4 12 12	5.3	5.4	22.64	26.43	2297				+82 0401 H
36	+83 0402	10.0 F8	13 52 29.431	+82 57 1.84	-0.0090	0.041	5 10 10	4.5	4.3	23.13	23.13	2300				+83 0360 H
37	+87 0136	10.2 A5	13 52 51.384	+86 29 25.25	-0.0033	0.000	4 07 07	3.0	3.0	32.62	28.92	2302				+86 0195 H
38	+82 0406	10.2 A5	+82 53 53.449	+82 1 59.73	-0.0031	0.004	8 11 11	5.0	4.8	26.58	26.58	2302				+82 0402 H
39	+82 0405	10.1 G5	+81 49 9.462	+81 49 9.462	-0.0014	-0.009	4 13 12	5.6	4.9	26.67	26.67	2304				+82 0403 H
40	+86 0203	12.3 K3	13 54 14.438	+85 25 54.81	0.0039	0.020	5 08 09	4.2	4.4	41.04	39.29	2311				+85 0217 H
41	+81 0454	11.1 F5	13 54 30.910	+80 46 37.67	0.0027	-0.008	4 12 12	5.4	5.5	24.15	26.00	2303				+81 0423 H
42	+88 0086	8.9 B9	13 54 57.133	+89 23 43.87	0.0062	0.007	7 07 07	3.1	3.2	34.04	33.94	2305	126047			+87 0108 D
43	+84 0319	12.3 G	13 55 4.668	+89 25 59.02	0.0169	-0.010	12 11 07	3.1	2.0	33.21	33.45	2302				+89 0040 H
44	+86 0204	11.6 K2	13 55 15.447	+82 4 42.30	-0.0033	-0.006	4 12 12	5.6	5.3	24.50	23.78	2313				+82 0404 H
45	+81 0455	11.2 F	13 55 18.114	+85 44 14.43	0.0036	-0.004	5 08 09	4.2	4.0	40.73	37.06	2305				+81 0423 H

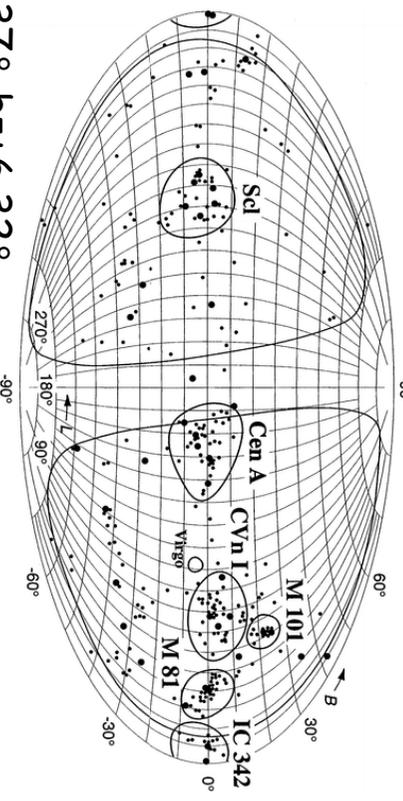
VI. The Supergalactic Frame

Equator aligned with the supergalactic plane formed by the nearby galaxy clusters Virgo, the Great Attractor and the Pisces-Perseus supercluster.

Coordinates: **supergalactic latitude SGB**
supergalactic longitude SGL

Zero point for SGL is the intersection of the supergalactic plane with the Galactic plane

The nearest 10 Mpc in SG coordinates



Definition:

North supergalactic pole at $l=47.37^\circ$, $b=+6.32^\circ$
or $RA=18.9^h$, $\delta=+15.7^\circ$ (J2000).

Zero point (SGB=0°, SGL=0°) at $l=137.37^\circ$, $b=0^\circ$
or $RA=2.82^h$, $\delta=+59.5^\circ$ (J2000).

Coordinate Frame Transformations

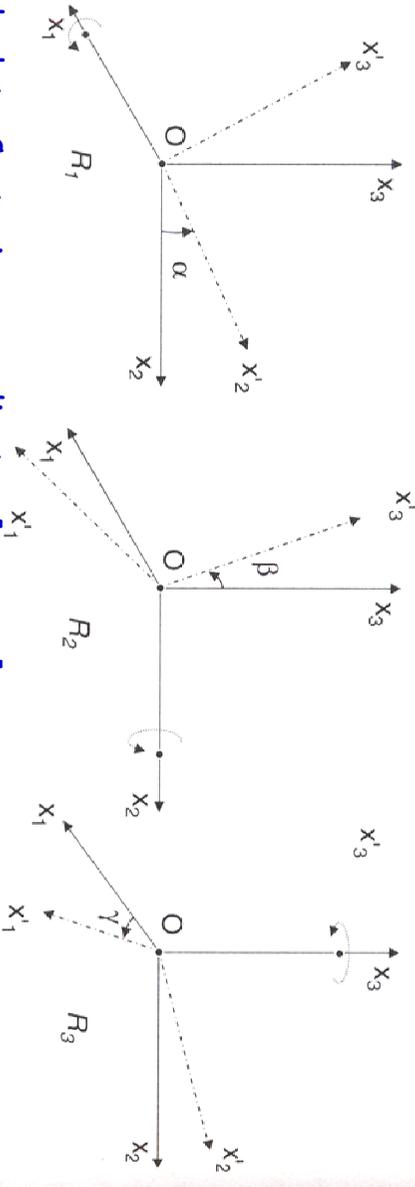
The hard way:

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = [R] \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$R_1(\alpha) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \alpha & \sin \alpha \\ 0 & -\sin \alpha & \cos \alpha \end{bmatrix}$$

$$R_2(\beta) = \begin{bmatrix} \cos \beta & 0 & -\sin \beta \\ 0 & 1 & 0 \\ \sin \beta & 0 & \cos \beta \end{bmatrix}$$

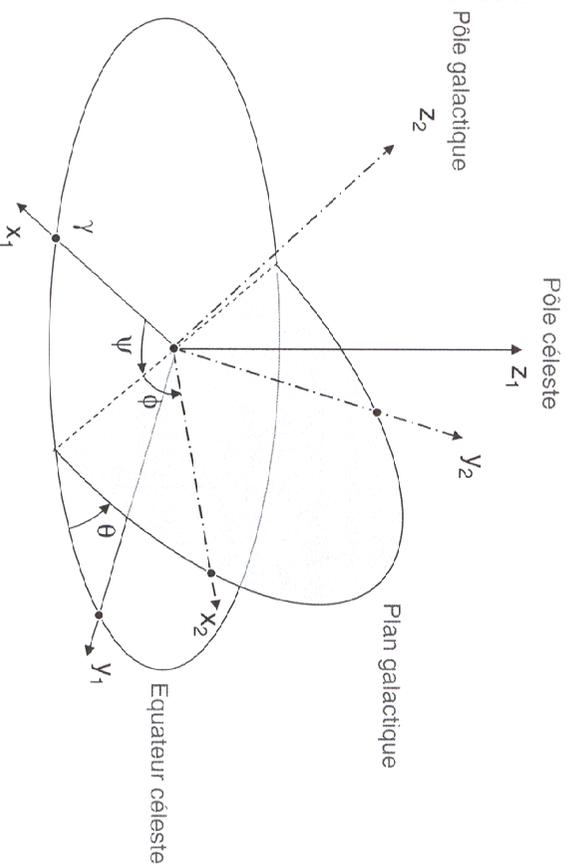
$$R_3(\gamma) = \begin{bmatrix} \cos \gamma & \sin \gamma & 0 \\ -\sin \gamma & \cos \gamma & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



1. Calculate Cartesian coordinates $[x_1, x_2, x_3]$
2. Apply rotation
3. Calculate transformed frame coordinates

→ see Monday exercises

Example: from Equatorial to Galactic Frame



$$U(\lambda, \beta) = R_3(\phi) \cdot R_1(\theta) \cdot R_3(\psi) U(\alpha, \delta)$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -0.05611 & -0.87374 & -0.48315 \\ 0.49333 & -0.44498 & 0.74741 \\ -0.86803 & -0.19642 & 0.45601 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

See book by Lena for details

Coordinate Frame Transformations (2)

The easy way: <http://heasarc.gsfc.nasa.gov/cgi-bin/Tools/convecord/convecord.pl>

Object Position Finder, Coordinate Converter, and Separation Calculator HELP

Single targets

Use this form to convert individual names or positions

Object Name or Coordinates:

Input Coordinate System: (e.g., Cyg X-1 or 101.295, -16.699 or 6.45 10.8, -16.41 58)

Name Resolvers: Use local caches

Special Equinox:

Lists

Use this form if you have a file with a list of coordinates or names.

Input coordinate System: Use local caches

Output coordinate System:

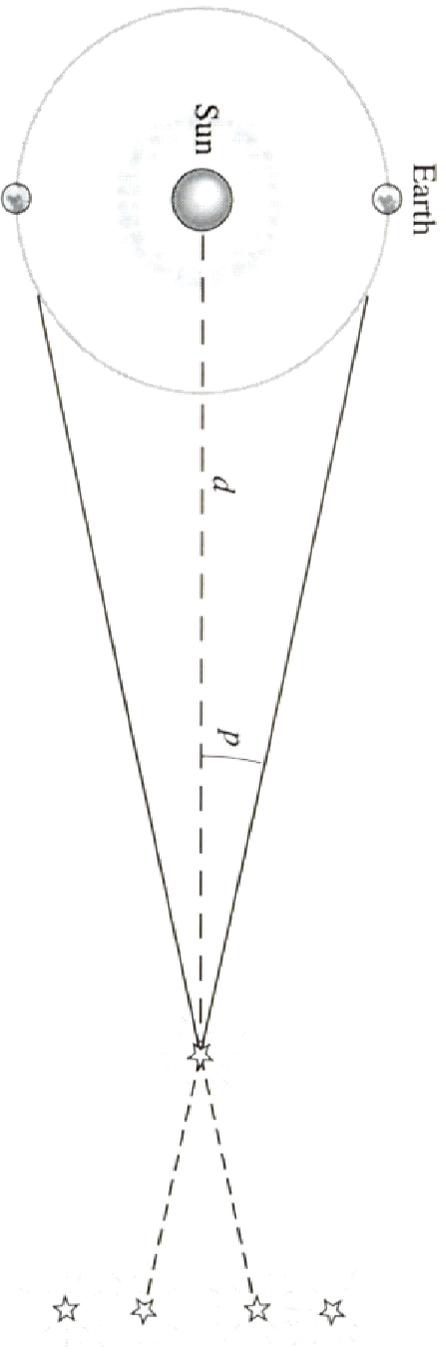
Output Options

12 34 56.7 / 12.34567 HTML / Text Output coordinates only

Input file:

Parallax and Orbital Motion

Parallax = semi-angle of inclination between two sightlines to a star.

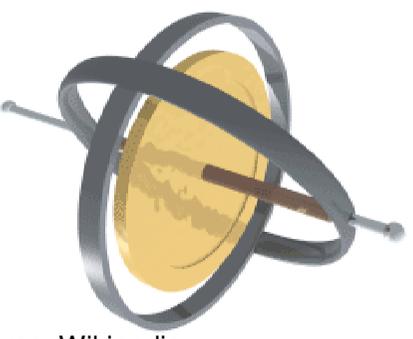


Stellar parallax: $d = 1/p''$ pc.

<http://www.astro.cornell.edu/academics/courses/astro101/nerter/java/parallax/parallax.html>

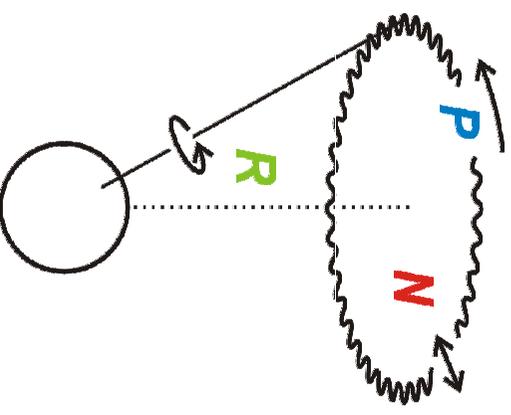
Precession and Nutation

Precession = movement of the direction of the Earth's rotational axis, caused mainly by Sun and Moon.
period: 25,764 years
magnitude: $\sim 50''$



source: Wikipedia

Nutation = tidal forces of Sun and Moon are continuously changing with their relative positions \rightarrow cause precession to vary over time.
period: 18.6 years (largest component)
magnitude: $\sim 9.2''$



NO

Position of the Sun - the Analemma

- circular orbit, no axial tilt: analemma is a dot
- circular orbit and axial tilt: analemma is a figure of eight; N and S lobes equal



- eccentric orbit, no axial tilt: analemma is a straight E-W line along the equator

SO

Photomontage illustrating an analemma pattern in the sky. Were one to take a photo of the sun each week for a year and combine the images taken, this pattern would be visible (from Wikipedia).



Ephemeris Time (ET)

The **ephemeris time** was defined by Simon Newcomb's (1898) tables* of the Earth's orbital motion around the Sun, later (more practically) by the orbital motion of the Moon around the Earth.

Definition:

One second (defined in 1900) = 1/31,556,925.9747 of the tropical year for 1900 January 0 at 12 hours ephemeris time. (since 1967 one uses atomic standards)

- One Julian day has 86,400 seconds
- One Julian century has 36,525 days
- One tropical year has 365.24219879 days

*an ephemeris is a table of values that gives the positions of astronomical objects in the sky at a given time

Universal Time (UT)

Timescale based on the rotation of the Earth.

Reference location is Greenwich meridian :

$UT = 12 \text{ hours} + \text{Greenwich hour angle}$

Ideally, noon Greenwich Mean Time is when the Sun crosses the Greenwich meridian.

But: variations in the Earth's orbit (nutaton, ellipticity, axial tilt) cause differences of up to 16 minutes.

→ Use Newcomb's fictitious mean Sun - hence also called *Greenwich mean time* G.M.T.)

Nowadays, use *atomic standards* - won't slow down but require occasional one second discontinuities to keep the Earth rotation in phase with atomic clocks → *UTC (coordinated universal time)*.



Sidereal Time (ST)

Sidereal time \equiv hour angle of the true vernal equinox

- The sidereal time is proportional to the UTC.
- It has the same value as the right ascension of any celestial body that is crossing the local meridian at that same moment.
- When one moves eastward 15° in longitude, the sidereal time increases by one hour.

Note: when $ST = RA$ the object will be at culmination.

When corrected for nutation → *mean sidereal time*.

Example: Local sidereal time (LST) at Leiden: $52^\circ 09' N$ $04^\circ 30' E$:

Use, e.g. <http://tycho.usno.navy.mil/sidereal.html> to check

Sidereal Day

Every 24.00 hr the Sun reaches the highest position in the South (= **synodic day**)

In the meantime, the Earth has rotated a bit more than 360 degrees as it orbits the Sun, (namely $360^\circ/365.25 = 0.986^\circ$).

Thus, a **sidereal day** is shorter:
 $24\text{hr} \cdot 360^\circ/360.986^\circ = 23\text{hr } 56\text{min}$

